

Intro :- unit :- 1 megapixels = 10^6 pixels
FPS = frames per second

09/08/2023

Computer Graphics :- Computer graphics are the graphics created using computers and the representation of image data by a computer specifically with help from specialized graphic hardware and software.

★ Uses of Computer graphics :-

- ↳ CAD (Computer Aided Design)
- ↳ Presentation graphics ↳ Computer art
- ↳ Entertainment industry ↳ Visualization
- ↳ Education & training ↳ GUI creation
- ↳ Image processing ↳ I/O devices

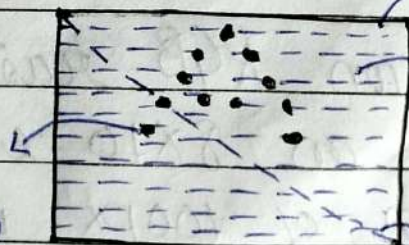
⇒ Cathode Ray Tube (CRT)

⇒ Aspect ratio = $\frac{\text{No. of horizontal line (Pixel)}}{\text{No. of vertical line (Pixel)}}$

• Persistence

⇒ Raster Scan :-

line grow at some point when they needed



line by line scanning

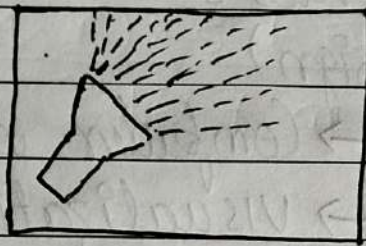
Horizontal extracting

vertical extracting

→ It also helps in refresh buffer (one to one mapping)

⇒ Interlaced Tracing System :- It traces alternatively like firstly it traces all odd line then even lines and then combine it.

⇒ Random Scan System :-



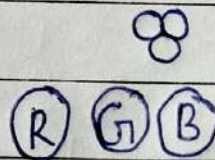
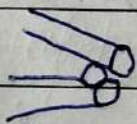
Information can store in display buffer in the form of commands

Color CRT monitor :-

→ Beam penetration → shadow masking
(Used with random scan monitors) (used with raster scan system)

⇒ Two methods :- (in shadow masking)

↳ Delta-Delta method ↳ Inline method



(Ques) Suppose an RGB raster system is to be design on 8x10 inch screen with a resolution of 100px per inch in each direction. If we want to store 6 bits

per pixel in the frame buffer. How much storage in bytes do we need in the frame buffer.

Solⁿ

8 $\Rightarrow 8 \times 10$ inches
 $\{ \because 8 \text{ bits} = 1 \text{ byte} \}$

\Rightarrow No. of pixels = $8 \times 10 \times 100 \times 100$

\Rightarrow Total no. of bits = $\frac{8 \times 10 \times 100 \times 100 \times 8}{8}$

\Rightarrow for one frame = 600000 ans//

(Ques 2) How long would it take to load a 640×480 frame buffer with 12 bits per px. If 10^5 bits can be transferred per s.

Solⁿ \Rightarrow Total no. of bits = $640 \times 480 \times 12$

\Rightarrow 1 sec = 10^5 bits transferred.

then,

\Rightarrow Time to load one frame buffer = $\frac{640 \times 480 \times 12}{10^5}$

\Rightarrow 36.864 seconds ans//

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(Ques 3) What is the fraction of the total refresh time per frame spent in refresh of e-beam for a non interlaced raster system with a resolution of 1280×1024 . A refresh rate of 60Hz a horizontal retrace time of 5000 microseconds and a vertical

refresh time of 500 micro seconds

$$\begin{aligned} \text{sol}^n \Rightarrow \text{Total refresh time} &= \text{Horizontal} + \text{Vertical} \\ &= 500 \mu\text{s} + 5 \mu\text{s} \\ &= 505 \mu\text{s} \end{aligned}$$

$$\Rightarrow \text{Refresh rate} = 60 \text{ Hz} = \frac{1}{60} \text{ sec to scan.}$$

$$1001 \times 1001 \times 01 = 16.7 \text{ sec}$$

$$\Rightarrow \text{Horizontal Retrace time} = (1024 - 1) \times 5 \mu\text{s}$$

$$\Rightarrow \text{Vertical Retrace time} = (1024 - 1) \times 5 \mu\text{s} + 500 \mu\text{s}$$

$$\Rightarrow (1024 - 1) \times 5 + 500 \mu\text{s}$$

16.7 ms

Program to Create a Pixel

```
#include <graphics.h>
```

```
void main ()
```

```
{ int gd = DETECT, gm;
```

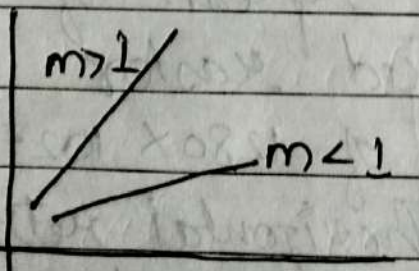
```
initgraph (&gd, &gm, "c:\\ + c\\log");
```

```
putpixel (x, y, RED);
```

↓ ↓
10 10

```
closegraph();
```

```
}
```

	When $m > 1$	When $m < 1$
	$x = \frac{y - c}{m}$	$y = mx + c$

#include <graphics.h>

#define ROUND(x) (int)(x+0.5)

void main()

{ int gd = DETECT, gm;

initgraph (&gd, &gm, "c:\\ + c\\ + bg");

putpixel (ROUND(x), ROUND(y), RED);

closegraph ();

}

#include <graphics.h>

void main()

{ float x, y, m, c, i, x1, x2, y1, y2;

scanf ("%.f %.f %.f %.f", &x1, &x2, &y1, &y2);

m = (y2 - y1) / (x2 - x1);

c = y1 - m * x1;

x = x1; y = y1;

if (m <= 1)

{ for (i = x1; i <= x2; i++)

{ putpixel (ROUND(x), ROUND(y), RED);

x++;

y = m * x + c;

}

else

{ for (i = y1; i <= y2; i++)

{ putpixel (ROUND(x), ROUND(y), RED);

y++;

x = (y - c) / m;

$\Rightarrow (x_1, y_1)$ to (x_2, y_2)

$$x = x_1 + (x_2 - x_1)u$$

$$y = y_1 + (y_2 - y_1)u$$

where $0 \leq u < 1$

$$u = u + du$$

$$du = \frac{1}{L} \quad \text{where } L = |dx| + |dy|$$

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Digital Differential analyzer (DDA)

$$\therefore y = mx + c$$

\Rightarrow if $m < 1$

$$\Rightarrow \frac{dy}{dx} = m \Rightarrow dy = m dx$$

$$\Rightarrow y_{n+1} - y_n = m(x_{n+1} - x_n)$$

for $m < 1$ $x_{n+1} = x_n + 1$

$$y_{n+1} - y_n = m(x_{n+1} - x_n)$$

$$y_{n+1} = y_n + m$$

\Rightarrow if $m > 1$

$$\Rightarrow y_{n+1} - y_n = (x_{n+1} - x_n)$$

for $m > 1$ $y_{n+1} = y_n + 1$

$$x_{n+1} = x_n + 1/m$$

```
void lineDDA (int xa, int xb, int ya, int yb)
{
    int dx = xb - xa, dy = yb - ya, steps, k;
    float xInc, yInc, x = xa, y = ya;
    if (abs(dx) > abs(dy)) steps = abs(dx);
    else steps = abs(dy);
}
```

```

else steps = abs(dy);
xInc = dx / (float) steps;
yInc = dy / (float) steps;
putpixel (ROUND(x), ROUND(y), RED);
for (k=0; k < steps; k++)
{
x = x + xInc;
y = y + yInc;
putpixel (ROUND(x), ROUND(y), RED);
}
}

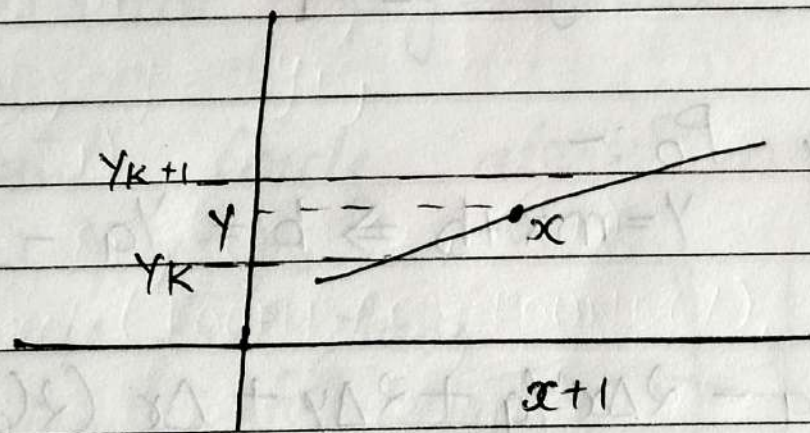
```

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Bresenham's line drawing algo

$$x_{k+1} = x_k + 1, \quad y_{k+1} = y_k + \frac{1}{y_k}$$

★ This algo is also known as integer line draw algo.



⇒ if $\Delta PK < 0$

⇒ $(x_k + 1, y_k)$

⇒ else

⇒ $(x_k + 1, y_k + 1)$ $\left\{ \because y = mx + b \right\}$

⇒ $d_1 = y - y_k \Rightarrow m(x_k + 1) + b - y_k$

⇒ $d_2 = (y_k + 1) - y \Rightarrow y_k + 1 - m(x_k + 1) - b$

$$\Rightarrow P_k = \Delta x (d_1 - d_2) = (2m(x_k + 1) - 2y_k + 2b - 1) \times \Delta x$$

$$\Rightarrow P_k = 2\Delta y x_k - 2\Delta x y_k + c$$

{ \because where $c = 2\Delta y + \Delta x (2b - 1)$ }

$$\Rightarrow P_{k+1} = 2\Delta y x_{k+1} - 2\Delta x y_{k+1} + c$$

$$\Rightarrow P_{k+1} - P_k = 2\Delta y (x_{k+1} - x_k) - 2\Delta x (y_{k+1} - y_k)$$

{ $\because x_{k+1} = x_k + 1$ }

$$\Rightarrow P_{k+1} = P_k + 2\Delta y - 2\Delta x (y_{k+1} - y_k)$$

\Rightarrow If $P_k < 0$ then $y_{k+1} = y_k$ and Point (x_{k+1}, y_k)

$$\Rightarrow \boxed{P_{k+1} = P_k + 2\Delta y}$$

\Rightarrow else then $y_{k+1} = y_k + 1$ and Point $(x_k + 1, y_k + 1)$

$$\Rightarrow \boxed{P_{k+1} = P_k + 2\Delta y - 2\Delta x}$$

\Rightarrow Calculating P_0 :-

$$\Rightarrow (x_a, y_a) \quad y = mx + b \Rightarrow b = y_a - \frac{\Delta y}{\Delta x} x_a$$

$$\Rightarrow P_0 = 2\Delta y x_a - 2\Delta x y_a + 2\Delta y + \Delta x (2(y_a - \frac{\Delta y}{\Delta x} x_a) - 1)$$

$$\Rightarrow \boxed{P_0 = 2\Delta y - \Delta x}$$

Program for drawing a circle

$$\Rightarrow x^2 + y^2 = r^2$$

$$\Rightarrow (x - x_c)^2 + (y - y_c)^2 = r^2$$

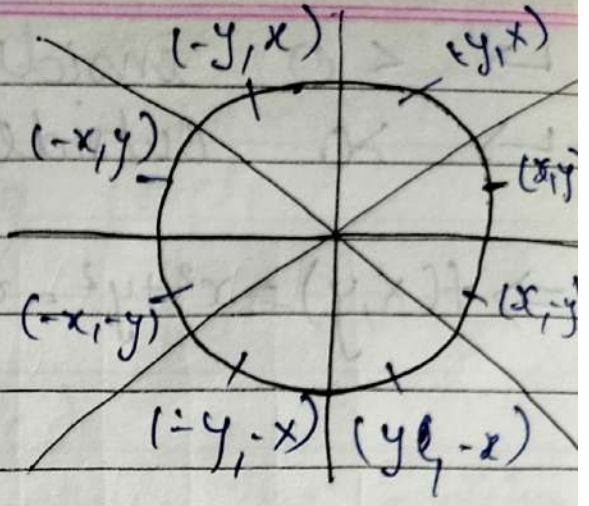
$$\Rightarrow x = \sqrt{r^2 - y^2}$$

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```

draw circle (int x, int y,
            int xc, int yc)
{
  putpixel(x+xc, y+yc, RED)
  putpixel(y+xc, x+yc, RED)
  ...
}

```



```

for (y=0; y<=x; y++)
{
  x = sqrt(x*x - y*y)
}

```

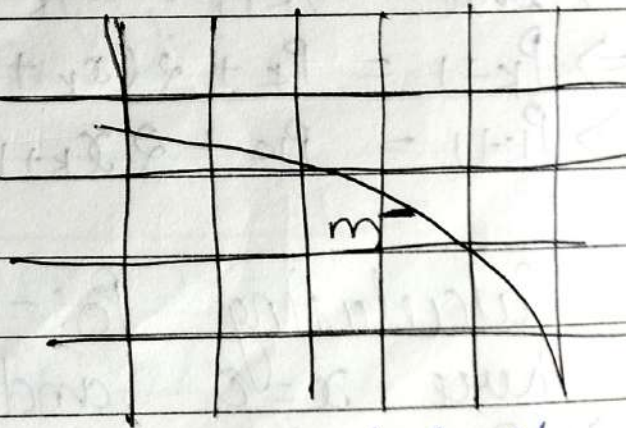
⇒ another eqn by which we can create circle.

$$x = r \sin \theta, \quad y = r \cos \theta.$$

Mid point circle algorithm

$$m(x_{k+1}, y_k - \frac{1}{2})$$

now if we put these coordinates into below eqn if $m < 0$ then m will go inside and we will take



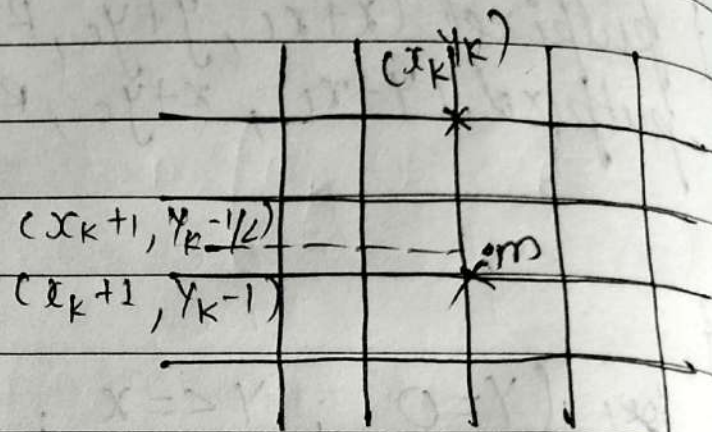
the ~~value~~ previous value of y and if it is outside the we will subtract 1 from y .

$$\text{eqn: } f(x, y) = x^2 + y^2 - r^2$$

$\hookrightarrow < 0$ inside (x_{k+1}, y_k)

$\hookrightarrow > 0$ outside (x_{k+1}, y_{k-1})

$$\Rightarrow f(x, y) = x^2 + y^2 = r^2$$



$$\Rightarrow P_k = f(x_{k+1}, y_{k-1/2}) = (x_{k+1})^2 + (y_{k-1/2})^2 - r^2$$

$$\Rightarrow P_{k+1} = f(x_{k+1} + 1, y_{k+1} - 1/2) = (x_{k+1} + 1)^2 + (y_{k+1} - 1/2)^2 - r^2$$

$$\Rightarrow \because x_{k+1} = x_k + 1$$

$$\Rightarrow P_{k+1} = P_k + 2(x_k + 1) + (y_{k+1}^2 - y_k^2) - (y_{k+1} - y_k) + 1$$

\Rightarrow If $P_k < 0$ then $y_{k+1} = y_k$, Points $(x_k + 1, y_k)$

$$\Rightarrow P_{k+1} = P_k + 2(x_k + 1) + 1$$

\Rightarrow else $y_{k+1} = y_k - 1$, Points $(x_k + 1, y_k - 1)$

$$\Rightarrow P_{k+1} = P_k + 2(x_k + 1) - 2(y_k - 1) + 1$$

$$\Rightarrow P_{k+1} = P_k + 2x_{k+1} - 2y_{k+1} + 1$$

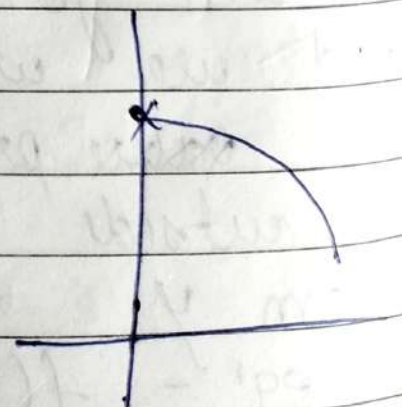
Calculating P_0 :-

here $x=0$, and $y=r$

$$\Rightarrow P_0 = f(0, r - 1/2)$$

$$\Rightarrow P_0 = 1 + (r - 1/2)^2 - r^2$$

$$\Rightarrow P_0 = \frac{5}{4} - r \approx 1 - r$$



$$P_0 = 1 - r$$

⇒ Algorithm for drawing circle:-

1. Read x_c, y_c, r
2. Calculate $P_0 = 1 - r$
3. draw circle $(0, r, x_c, y_c)$
4. make a while loop where the condition will be $x \neq r$. or use for loop where $x = 0$; $x \leq r$ and $x++$

⇒ Program for drawing circle

```
void midpoint (int xc, int yc, int r) {
```

```
int p = 1 - r, x = 0, y = r;
```

```
drawCircle(x, y, xc, yc) {
```

```
for (x = 0; x <= r; x++) {
```

```
if (p < 0) {
```

```
    p = p + 2(x + 1) + 1;
```

```
    x++;
```

```
    drawCircle(x, y, xc, yc);
```

```
else { y = y - 1;
```

```
    x++;
```

```
    p = p + 2(x + 1) - 2(y - 1) + 1
```

```
    drawCircle(x, y, xc, yc);
```

```
} }
```

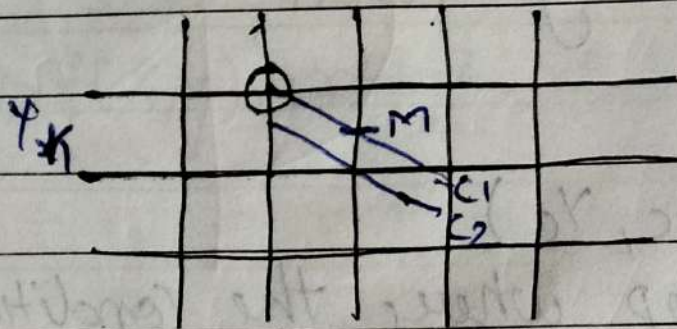
```
PutPixel(x + xc, y + yc, RED)
```

```
    " (-x + xc, y + yc, " )
```

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$$= (-x + \alpha c, -y + \gamma c, \dots)$$

$$= (x + \alpha c, -y + \gamma c, \dots)$$



$$m \left(x_k + 1, y_k - \frac{1}{2} \right)$$

$$\Rightarrow f(x, y) = x^2 \delta y^2 + y^2 \delta x^2 - \delta x^2 \delta y^2$$

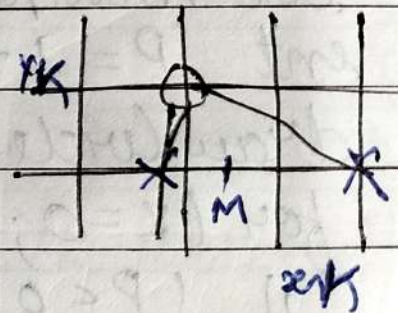
$$\Rightarrow f(m) < 0 \quad (x_k + 1, y_k) \quad \text{for } R_1$$

$$f(m) > 0 \quad (x_k + 1, y_k - 1) \quad \text{region}$$

for R_2 region

$$f(m) < 0 \quad (x_k + 1, y_k - 1)$$

$$f(m) > 0 \quad (x_k, y_k - 1)$$



$$m \left(x_k + \frac{1}{2}, y_k - 1 \right)$$

Now parameter of decision

↳ decision parameters are

$$P_{\perp k} = f \left(x_k + 1, y_k - \frac{1}{2} \right) \Rightarrow (x_k + 1)^2 \delta y^2 + \left(y_k - \frac{1}{2} \right)^2 \delta x^2 - \delta x^2 \delta y^2$$

$$P'_{\perp k+1} = f \left(x_{k+1}, y_{k+1} - \frac{1}{2} \right)$$

$$P_{\perp k+1} - P_k$$

If $P_{1k} < 0$ then

$$\Rightarrow P_{1k+1} = P_{1k} + 2\sigma_y^2 x_{k+1} + \sigma_y^2$$

$$= P_{1k} + 2\sigma_y^2 (x_k + 1) + \sigma_y^2$$

else $\therefore [x_{k+1} = x_k + 1]$

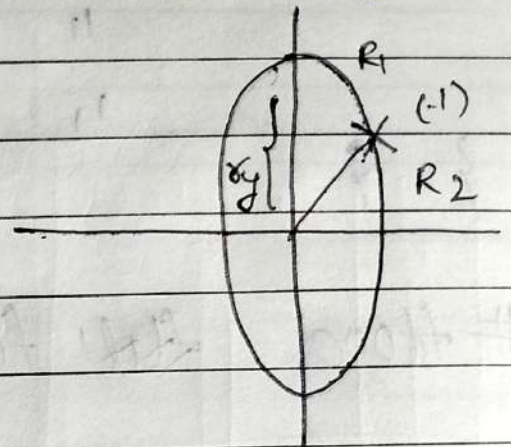
$$P_{1k+1} = P_{1k} + 2\sigma_y^2 x_{k+1} + \sigma_y^2 - 2\sigma_x^2 y_{k+1}$$

$[y_{k+1} = y_k + 1]$

Now,

Since $x = 0, y = \sigma_y$
then

$$f(0+1, \sigma_y - 1/2)$$

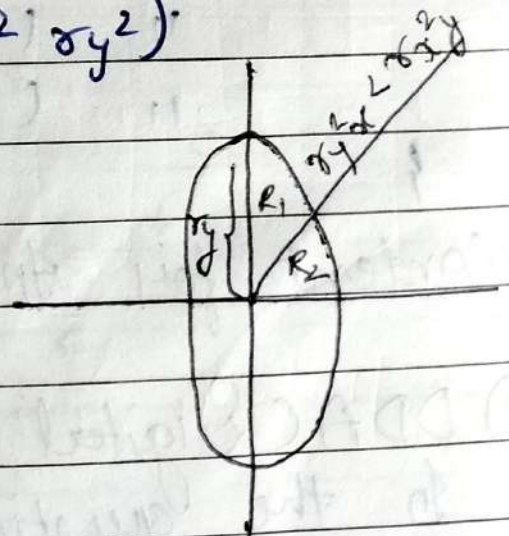


Now same for finding P_2 (decision parameter two)

\Rightarrow for finding slope i.e. m

$$\frac{dy}{dx} = \frac{d(x^2 \sigma_y^2 + y^2 \sigma_x^2 - \sigma_x^2 \sigma_y^2)}{dx}$$

$$= \frac{2\sigma_y^2 x}{2\sigma_x^2 y} = -1$$



Boundary fill Algo

```

void fullBoundary (int x, int y, int fillColor, int boundaryC)
{
    int currentC = full getPixel (x, y);
    if (currentC != boundaryC && currentC != fillColor)
    {
        putPixel (x, y, fillColor);
        fullBoundary (x-1, y, fullBoundaryC);
        " (x+1, y, " " " );
        " (x, y+1, " " " );
        " (x, y-1, " " " );
    }
}

```

flood fill Algo

```

void fullflood (int x, int y, int oldColor, int fillColor)
{
    if (getPixel (x, y) == oldColor)
    {
        putPixel (x, y, fillColor);
        fullflood (x-1, x, oldColor, fillColor);
        " (x+1, y, " " " );
        " (x, y+1, " " " );
        " (x, y-1, " " " );
    }
}

```

13/09/23

Content for Internal :-

① DDAC (Digital Differential Analyses) :-
In the question we are given with the

Points of line

ex^o - (1,1) and (3,3)

step 1^o - calculate slope (m) = $\frac{\Delta y}{\Delta x} = \frac{y_2 - y_1}{x_2 - x_1}$

$$\Rightarrow m = \frac{3-1}{3-1} = \frac{2}{2} \Rightarrow 1$$

step 2^o - find Δx and Δy

$$\Rightarrow \Delta x = \frac{\Delta y}{m} = \Delta y \frac{x_2 - x_1}{y_2 - y_1} \left(\because m = \frac{y_2 - y_1}{x_2 - x_1} \right)$$

$$\Rightarrow \Delta x = x_2 - x_1 \Rightarrow 2$$

$$\Rightarrow \Delta y = m \Delta x = \frac{y_2 - y_1}{x_2 - x_1} \Delta x = y_2 - y_1$$

$$\Rightarrow \Delta y = 2$$

step 3^o - $|\Delta x| \geq |\Delta y|$, so assign $\Delta x = 1$

there are 2 cases

case 1:- if $|\Delta x| \geq |\Delta y|$ then assign $\Delta x = 1$

$$\Rightarrow x_{i+1} = x_i + \Delta x$$

$$\Rightarrow x_{i+1} = x_i + 1$$

$$\Rightarrow y_{i+1} = y_i + \Delta y = y_i + m \Delta x$$

$$\Rightarrow y_{i+1} = y_i + m$$

case 2:- if $|\Delta x| < |\Delta y|$ then assign $\Delta y = 1$

$$\Rightarrow x_{i+1} = x_i + \Delta x = x_i + \frac{\Delta y}{m}$$

$$\Rightarrow x_{i+1} = x_i + 1/m$$

$$\Rightarrow y_{i+1} = y_i + \Delta y$$

$$\Rightarrow y_{i+1} = y_i + 1$$

In this question we are having case 1 that why we have assigned $\Delta x = 1$

$$\Rightarrow x_{i+1} = x_i + 1 \quad \Rightarrow y_{i+1} = y_i + m$$

$$\Rightarrow x_{i+1} = 1 + 1 = 2 // \quad \Rightarrow y_{i+1} = 1 + 1 = 2 //$$

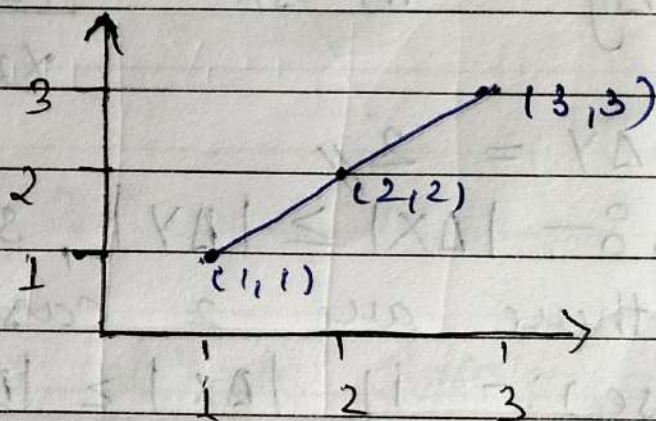
again calculating with the updated values of x_i and y_i

$$\Rightarrow x_{i+1} = x_i + 1 = 2 + 1 \quad \Rightarrow y_{i+1} = y_i + m = 2 + 1$$

$$\Rightarrow x_{i+1} = 3 \quad \Rightarrow y_{i+1} = 3$$

Now the points are $(1, 1)$, $(2, 2)$ and $(3, 3)$

x_i	y_i	x_{i+1}	y_{i+1}
1	1	2	2
2	2	3	3



Q2) Bresenham's line drawing algorithm

In DDA in most of the cases the points are in floating point which cause problem that why we had Bresenham's algorithm
ex:- $(1, 1)$ and $(5, 3)$

step 1:- calculate slope (m) = $\frac{\Delta y}{\Delta x} = \frac{y_2 - y_1}{x_2 - x_1}$

$$\Rightarrow m = \frac{3 - 1}{5 - 1} = \frac{2}{4} = \frac{1}{2} = 0.5 \Rightarrow \boxed{m = 0.5}$$

step 2:- calculate Decision Parameter (P)

$$P = 2\Delta y - \Delta x$$

Now there are 2 cases:-

Case 1:- $0 < m < 1$

(a) $P < 0$

$$x_{i+1} = x_i + 1$$

$$y_{i+1} = y_i$$

$$P_{k+1} = P_k + 2\Delta y$$

(b) $P \geq 0$

$$x_{i+1} = x_i + 1$$

$$y_{i+1} = y_i + 1$$

$$P_{k+1} = P_k + 2\Delta y - 2\Delta x$$

Case 2:-

(a) $m \geq 1$

(a) $P < 0$

$$x_{i+1} = x_i$$

$$y_{i+1} = y_i + 1$$

$$P_{k+1} = P_k + 2\Delta x$$

(b) $P \geq 0$

$$x_{i+1} = x_i + 1$$

$$y_{i+1} = y_i + 1$$

$$P_{k+1} = P_k + 2\Delta x - \Delta y$$

\Rightarrow Our $m = 0.5 < 1$ so we'll follow case 1

so now let us check the value of P

$$\Rightarrow P = 2\Delta y - \Delta x = 2(y_2 - y_1) - (x_2 - x_1)$$

$$\Rightarrow P = 2(3 - 1) - (5 - 1) = 2(2) - 4 = 0$$

$$\Rightarrow \boxed{P = 0}$$

now we will follow the (b) part of case 1
as our $P = 0$

\Rightarrow Now we will calculate $x_{i+1}, y_{i+1}, P_{k+1}$

$$\Rightarrow x_{i+1} = x_i + 1 = 1 + 1 \Rightarrow \boxed{x_{i+1} = 2}$$

$$\Rightarrow y_{i+1} = y_i + 1 = 1 + 1 \Rightarrow \boxed{y_{i+1} = 2}$$

$$\Rightarrow P_{k+1} = P_k + 2\Delta y - 2\Delta x = 0 + 2(2) - 2(4)$$

$$\Rightarrow P_{k+1} = 4 - 8 \Rightarrow \boxed{P_{k+1} = -4}$$

Now $P < 0$ so (a) part will be followed

$$\Rightarrow x_{i+1} = x_i + 1 = 2 + 1 \Rightarrow \boxed{x_{i+1} = 3}$$

$$\Rightarrow y_{i+1} = y_i \Rightarrow \boxed{y_{i+1} = 2}$$

$$\Rightarrow P_{k+1} = P_k + 2\Delta y \Rightarrow P_{k+1} = -4 + 2(2) = 0$$

now $P=0$ so following part (b)

$$\Rightarrow x_{i+1} = x_i + 1 = 3 + 1 \Rightarrow \boxed{x_{i+1} = 4}$$

$$\Rightarrow y_{i+1} = y_i + 1 = 2 + 1 \Rightarrow \boxed{y_{i+1} = 3}$$

$$\Rightarrow P_{k+1} = P_k + 2\Delta y - 2\Delta x \Rightarrow -0 + 4 - 8$$

$$\Rightarrow \boxed{P_{k+1} = -4}$$

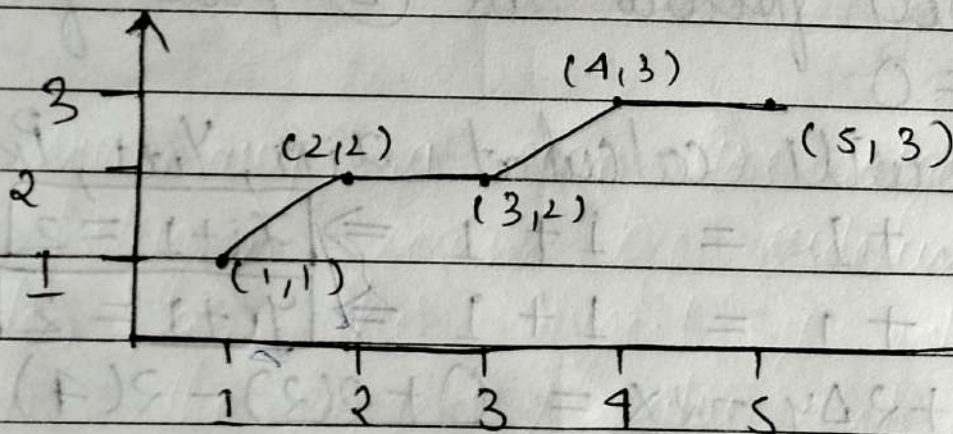
$P_k < 0$ so following part (a)

$$\Rightarrow x_{i+1} = x_i + 1 = 4 + 1 = 5 \Rightarrow \boxed{x_{i+1} = 5}$$

$$\Rightarrow y_{i+1} = y_i = 3 \Rightarrow \boxed{y_{i+1} = 3}$$

Our points are $(1, 1)$, $(2, 2)$, $(3, 2)$, $(4, 3)$ and $(5, 3)$

P	x_i	y_i	x_{i+1}	y_{i+1}
0	1	1	2	2
-4	2	2	3	2
0	3	2	4	3
-4	4	3	5	3



3) Mid point circle drawing algorithm

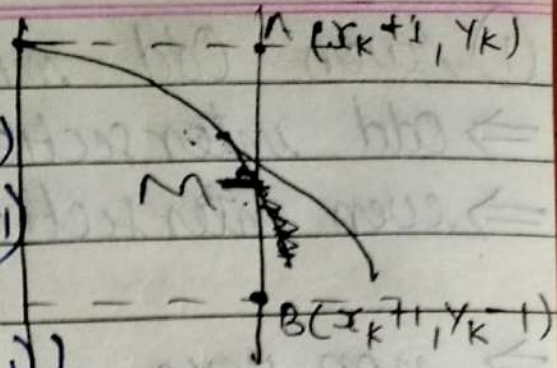
$$\Rightarrow x^2 + y^2 = r^2 \text{ --- (1)} \Rightarrow x^2 + y^2 - r^2 = 0 \text{ --- (2)}$$

point of M = (x_m, y_m)

$$\Rightarrow (x_m)^2 + (y_m)^2 - r^2 = 0 \text{ --- (3)}$$

if the result of eqn (3) are

- 0 : Point lies on a circle
- < 0 : Point lies inside (x_{k+1}, y_k)
- > 0 : Point lies outside (x_{k+1}, y_{k+1})



⇒ Midpoint = $\left(\frac{x_k + 1, x_{k+1}}{2}, \frac{(y_k + y_{k+1})}{2} \right)$
 coordinate

= $(x_k + 1, y_k - 1/2)$ ($\because d_k = \text{decision parameter}$)

⇒ $d_k = (x_k + 1)^2 + (y_k - 1/2)^2 - r^2$ — (4)

⇒ $d_{k+1} = (x_{k+1} + 1)^2 + (y_{k+1} - 1/2)^2 - r^2$

⇒ $d_{k+1} - d_k$

after solving this we get

⇒ $d_{k+1} = d_k + 2x_k + 3 + (y_k + 1)^2 - y_{k+1} - y_k^2 + y_k$

- if $d_k < 0$ then $y_{k+1} = y_k$

⇒ $d_{k+1} = d_k + 2x_k + 3$

- if $d_k > 0$ then $y_{k+1} = y_k - 1$

⇒ $d_{k+1} = d_k + 2x_k - 2y_k + 5$

⇒ $(0, r)$ IDP (d_0) { IDP = Initial decision Parameter }

Put $(0, r)$ in eqn (4)

⇒ $d_0 = (0+1)^2 + (r - 1/2)^2 - r^2$

⇒ $d_0 = 5/4 - r$

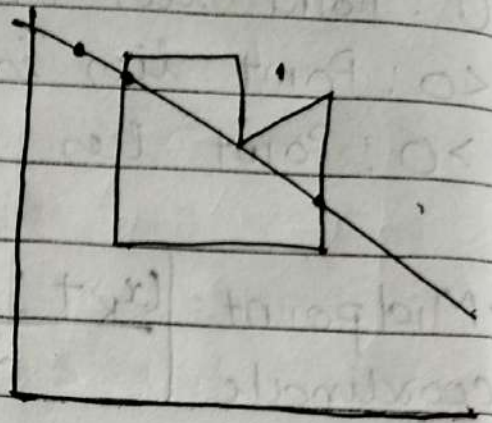
25/09/2023

How to find a point inside a polygon or outside a polygon

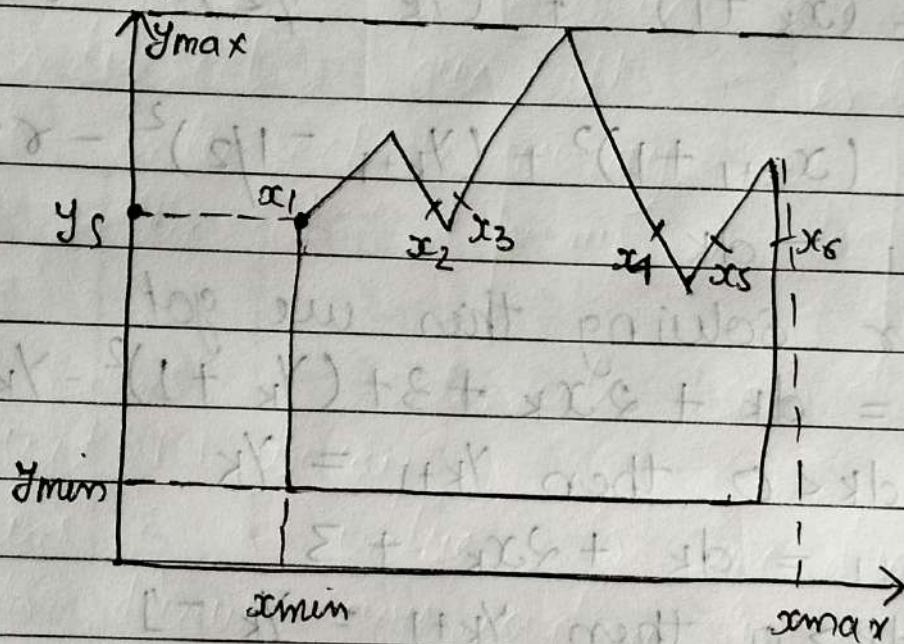
① Even Odd method

⇒ odd intersection = In
⇒ even intersection = Out

⇒ non zero = inside
⇒ zero = outside



Scan line Algorithm:-



In summary, a scan line algorithm for filling a polygon begins by ordering the polygon sides on the largest y value. It begins with the largest y value and scans down the polygon. For each y, it determines which sides can be intersected and finds the x values of these intersection points. It then sorts, pairs and passes these x values to a line drawing routine.

⇒ Scan line Conversion Algorithm for polygon

filling :-

1. Read n , the number of vertices of polygon
2. Read x and y coordinates of all vertices
in array $x[n]$ and $y[n]$
3. find y_{min} and y_{max}
4. Store the initial x values (x_1) y values y_1 and y_2 for two endpoints and x increment Δx from scan line for each edge in the array
edges $[n][4]$

while doing this check that $y_1 > y_2$ if not interchange y_1 and y_2 and corresponding x_1 and x_2 so that for each edge, y_1 represents its maximum y coordinate and y_2 represents its minimum y coordinate

5. Sort the rows of arrays, edges $[n][4]$ in descending order of y_1 , descending order of y_2 and ascending order of x_2
6. Set $y = y_{max}$
7. find the active edges and update active edge list

if ($y > y_2$ and $y \leq y_1$)

edge is active

else

edge is not active

8. compute the x intersects for all active edges for current y values initially x intersects

is x_i and x intersect for successive y values can be given as.

$$x_{i+1} = x_i + \Delta x$$

$$\text{where } \Delta x = \frac{-1}{m} \text{ and } m = \frac{y_2 - y_1}{x_2 - x_1} \text{ i.e.}$$

slope of a line segment

9. If x intersect is vertex i.e. x -intersect $= x_1$ and $y = y_1$, then apply vertex test to check whether to consider one intersect or two intersect. Store all x intersect in the x -intersect $\{ \}$ array

10. Sort x -intersect $\{ \}$ array in the ascending order

11. Extract pairs of intersects from the sorted x -intersect $[]$ array

12. Pass pairs of x value to line drawing routine to draw corresponding line segments

13. Set $y = y - 1$

14. Repeat steps 7 through 13 until $y \geq y_{\min}$

15. Stop.

.03/10/2023

QD Transformation

$$x' = r \cos(\phi + \theta) \Rightarrow r \cos \phi \cos \theta - r \sin \phi \sin \theta$$

$$y' = r \sin(\phi + \theta) \Rightarrow r \cos \phi \sin \theta + r \sin \phi \cos \theta$$

$$x = r \cos \phi$$

$$y = r \sin \phi$$

$$\left. \begin{aligned} x' &= x \cos \theta - y \sin \theta \\ y' &= x \sin \theta + y \cos \theta \end{aligned} \right\} \begin{aligned} X'Y' &= [X \ Y] \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \\ P' &= P \times R \end{aligned}$$

→ Scaling an object :-

$$x' = x \times S_x$$

$$y' = y \times S_y$$

$$[x' \ y'] = [x \ y] \begin{bmatrix} S_x & 0 \\ 0 & S_y \end{bmatrix}$$

$$P' = P \times S$$

S_x and S_y are scaling factors.

Ques :- Scale the triangle with coordinates
 $A(2, 5)$, $B(7, 10)$, $C(10, 2)$ by 2 unit
 in x direction and 2 unit in y
 direction

Solⁿ $P' = P \times S$

$$\begin{array}{l} A' \\ B' \\ C' \end{array} \begin{bmatrix} x_1' & y_1' \\ x_2' & y_2' \\ x_3' & y_3' \end{bmatrix} = \begin{bmatrix} 2 & 5 \\ 7 & 10 \\ 10 & 2 \end{bmatrix} \times \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} = \begin{bmatrix} 4 & 10 \\ 14 & 20 \\ 20 & 4 \end{bmatrix} \begin{array}{l} A \\ B \\ C \end{array}$$

New coordinates are :-

$A(4, 10)$; $B(14, 20)$; $C(20, 4)$

⇒ Homogeneous Coordinate

$$[x_w \ y_w \ w]$$

$$T = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ t_x & t_y & 1 \end{bmatrix}$$

$$x = \frac{x_w}{w}, \quad y = \frac{y_w}{w}$$

$$[x \ y \ 1]$$

$$R = \begin{bmatrix} \cos\theta & \sin\theta & 0 \\ -\sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$P' = P \times$ Transformable
Matrix

$$S = \begin{bmatrix} s_x & 0 & 0 \\ 0 & s_y & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\Rightarrow P' = P \times T$$

$$\Rightarrow P' = P \times R$$

$$\Rightarrow P' = P \times S$$

$$P' = P \cdot M_1 + M_2$$

$M_1 =$ Identity Matrix

$M_2 =$ Translation Vector

$$P' = P \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} t_x \\ t_y \end{bmatrix} \quad \text{translation}$$

$$P' = P \begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \text{Rotation}$$

$$P' = P \begin{bmatrix} s_x & 0 \\ 0 & s_y \end{bmatrix}$$

I refer previous Ques. but here we have to do

① $t_x = 5$, $t_y = 3$ and ② $s_x = 2$, $s_y = 1/2$

Solⁿ first calculate $CM = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 5 & 3 & 1 \end{bmatrix} \times \begin{bmatrix} 2 & 0 & 0 \\ 0 & 1/2 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

$$\Rightarrow P' = P \times CM$$

$$\begin{matrix} A' \\ B' \\ C' \end{matrix} \begin{bmatrix} x_1' & y_1' \\ x_2' & y_2' \\ x_3' & y_3' \end{bmatrix} = \begin{bmatrix} 2 & 5 & 1 \\ 4 & 10 & 1 \\ 10 & 2 & 1 \end{bmatrix} \times \begin{bmatrix} CM \end{bmatrix}$$

04/10/2023

I find the transformation matrix that transform the square ABCD to half its size with centre still remaining at the same position. The coordinates of square are $A(1,1)$; $B(3,1)$; $C(3,3)$; $D(1,3)$ and center at $(2,2)$ also find the resultant coordinate of square.

Solⁿ $CM = T_{(-2,-2)}^{-1} \times S_{(1/2, 1/2)} \times T_{(2,2)}$

$$\Rightarrow CM = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -2 & -2 & 1 \end{bmatrix} \times \begin{bmatrix} 1/2 & 0 & 0 \\ 0 & 1/2 & 0 \\ 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 2 & 0 & 1 \end{bmatrix}$$

$$\Rightarrow CM = \begin{bmatrix} 0.5 & 0 & 0 \\ 0 & 0.5 & 0 \\ 1 & 1 & 1 \end{bmatrix}$$

$$P' = P \times CM$$

$$\begin{bmatrix} A' \\ B' \\ C' \\ D' \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 3 & 1 & 1 \\ 3 & 3 & 1 \\ 1 & 3 & 1 \end{bmatrix} \times \begin{bmatrix} 0.5 & 0 & 0 \\ 0 & 0.5 & 0 \\ 1 & 1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1.5 & 1.5 & 1 \\ 2.5 & 1.5 & 1 \\ 2.5 & 2.5 & 1 \\ 1.5 & 2.5 & 1 \end{bmatrix}$$

$$A(1.5, 1.5)$$

$$B(2.5, 1.5)$$

$$C(2.5, 2.5)$$

$$D(1.5, 2.5)$$

ans

Now rotate that square by 45°

$$CM = T^{-1} \times R \times T$$

$(-2, -2) \quad (45^\circ) \quad (2, 2)$

$$\Rightarrow CM = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -2 & -2 & 1 \end{bmatrix} \times \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} & 0 \\ -1/\sqrt{2} & 1/\sqrt{2} & 0 \\ 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 2 & 2 & 1 \end{bmatrix}$$

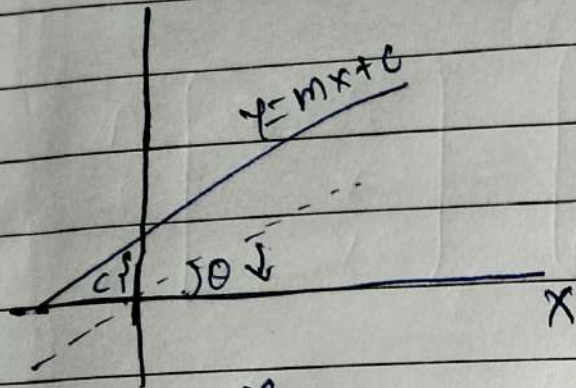
then calculate CM and P'

Q) find a transformation of ΔA_1O
 $B_0, 1 \quad C_1, 1$

Q) Rotating 45° about origin then translating

1 unit in x direction and y direction
 (b) translate in 1 unit in x and y direction and then rotate 45° about the origin
 05/10/2023

Reflection



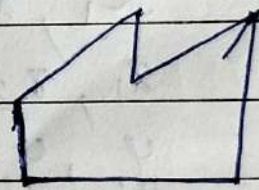
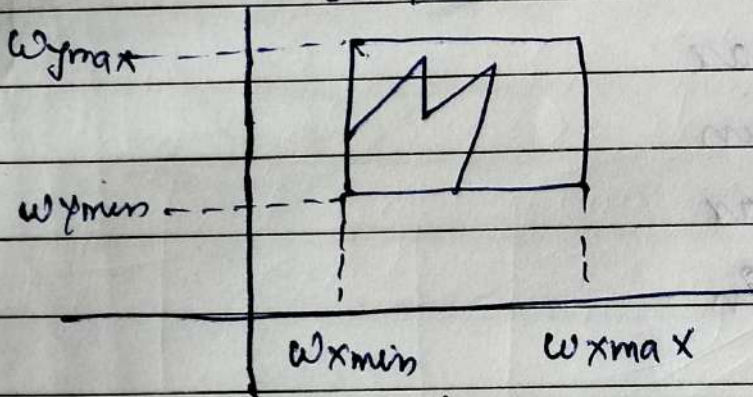
$$m = \tan \theta$$

$$\theta = \tan^{-1} m$$

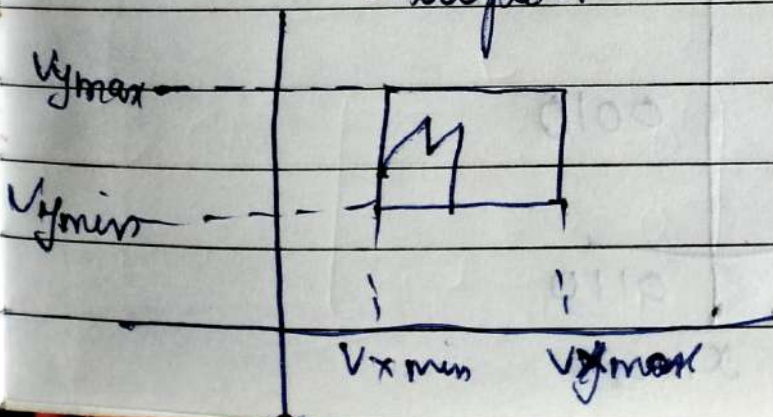
$$C_m = T(0, -c) \times R(-\theta) \times Ref_x \times R(\theta) \times T(0, c)$$

Windowing and Clipping

original image



viewport



$$C_m = T_{(-W_{xmin} - W_{ymmin})} \times S_{(sx, sy)} \times T_{(W_{xmax} - W_{ymax})}$$

$$\Rightarrow sx = \frac{W_{xmax} - W_{xmin}}{W_{xmax} - W_{xmin}}$$

$$\Rightarrow sy = \frac{W_{ymax} - W_{ymmin}}{W_{ymax} - W_{ymmin}}$$

→ Point clipping :-

$$W_{xmin} \leq x \leq W_{xmax}$$

$$W_{ymmin} \leq y \leq W_{ymax}$$

09/10/2023

Cohen Sutherland line clipping Algo

$$x_1, x_2 > x_{max}$$

$$x_1, x_2 < x_{min}$$

$$y_1, y_2 > y_{max}$$

$$y_1, y_2 < y_{min}$$

TBRL

y_{max}	1000	1010
000	0000	0010
y_{min}	0100	0110

Visible \Rightarrow 0000

Not Visible \Rightarrow Bitwise AND Non zero

$$x_i = x_{min} \text{ or } x_{max}$$

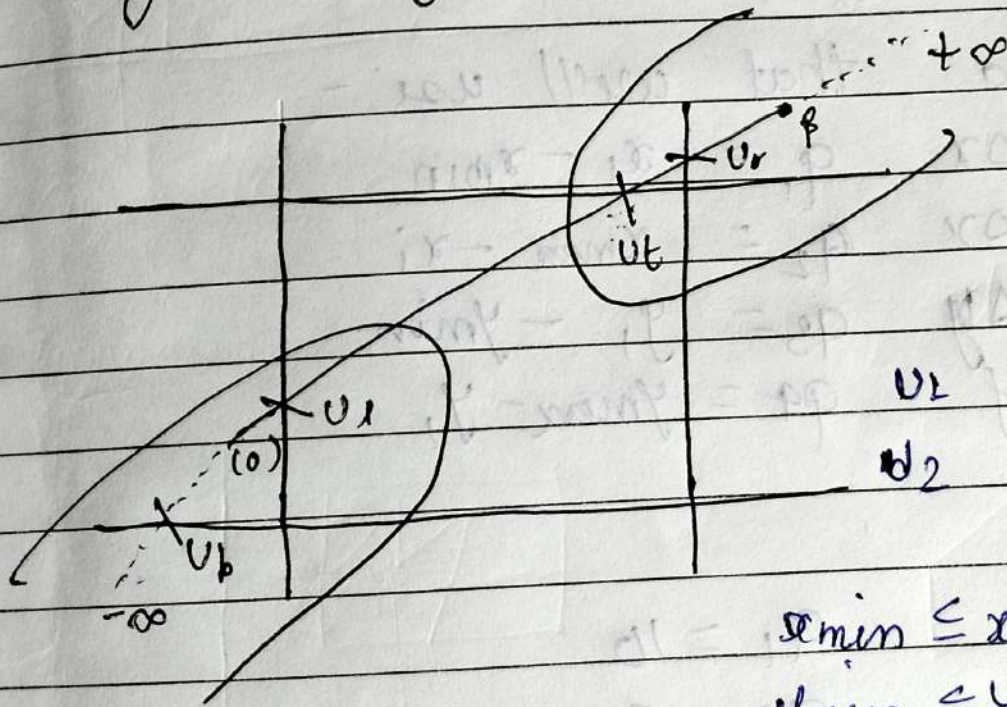
$$y_i = y_1 + m(x_i - x_1)$$

and

$$x_i = x_1 + (y_i - y_1) / m$$

$$y_i = y_{min} \text{ or } y_{max}$$

Liang Barsky line clipping equation



$$x = x_1 + \Delta x u$$

$$y = y_1 + \Delta y u$$

$$u_L = \max(u_b, u_t, 0)$$

$$u_R = \min(1, u_r, u_l)$$

$$x_{min} \leq x_1 + \Delta x u \leq x_{max}$$

$$y_{min} \leq y_1 + \Delta y u \leq y_{max}$$

$$P_k \cdot u \leq Q_k \quad k = 1, 2, 3, 4$$

$$\Rightarrow P_1 = -\Delta x \quad Q_1 = x_1 - x_{max} \quad (\text{left})$$

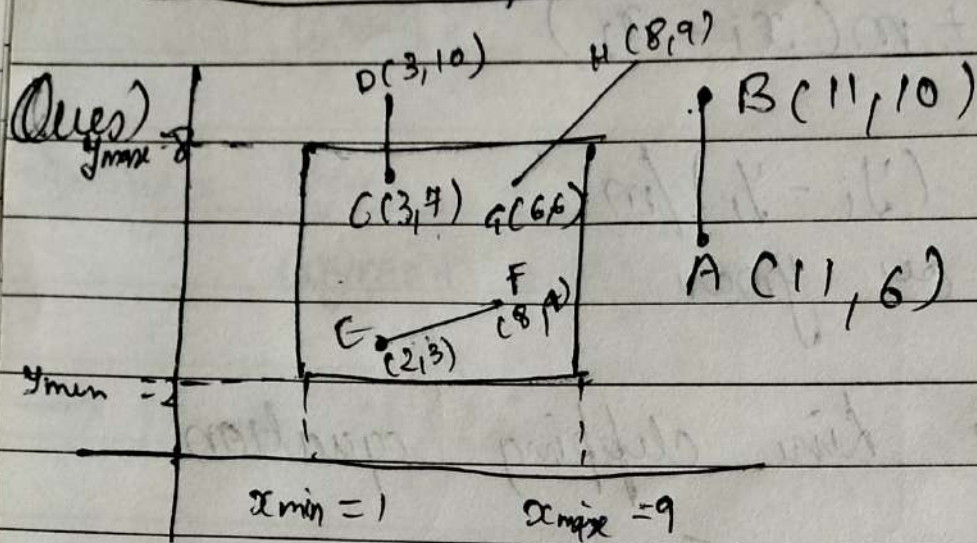
$$\Rightarrow P_2 = \Delta x \quad Q_2 = x_{max} - x_1 \quad (\text{right})$$

$$\Rightarrow P_3 = -\Delta y \quad Q_3 = y_1 - y_{min} \quad (\text{bottom})$$

$$\Rightarrow P_4 = \Delta y \quad Q_4 = y_{max} - y_1 \quad (\text{top})$$

$$\Rightarrow -\Delta x \quad 0 \leq x_1 - x_{\min}$$

$$\Rightarrow \boxed{x_{\min} \leq x_1 + \Delta x_4}$$



Soln formula that we'll use:-

$$P_1 = -\Delta x \quad Q_1 = x_1 - x_{\min}$$

$$P_2 = -\Delta y \quad Q_2 = x_{\max} - x_1$$

$$P_3 = -\Delta y \quad Q_3 = y_1 - y_{\min}$$

$$P_4 = \Delta y \quad Q_4 = y_{\max} - y_1$$

\Rightarrow for AB

$$P_1 = 0 \quad Q_1 = 10$$

$$P_2 = 0 \quad Q_2 = -2$$

$$P_3 = -4 \quad Q_3 = 4$$

$$P_4 = 4 \quad Q_4 = 2$$

\Rightarrow for CD

$$P_1 = 0 \quad Q_1 = 3$$

$$P_2 = 0 \quad Q_2 = 6$$

$$P_3 = -3 \quad Q_3 = 5$$

$$P_4 = 3 \quad Q_4 = 1$$

calculating r :- for P_3 because $P_3 = -ve$
 $\Rightarrow r = \frac{5}{3} \Rightarrow u_1 = \max(0 \text{ and } -5/3) = 0$

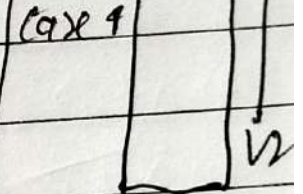
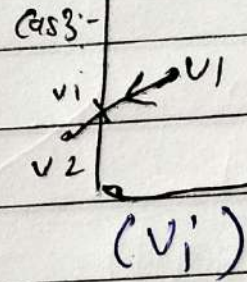
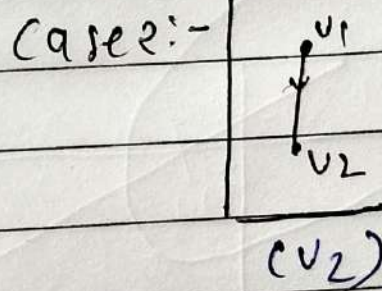
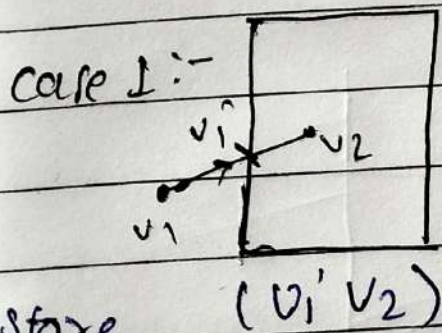
$\Rightarrow r = \frac{1}{3} \Rightarrow u_2 = \min(1 \text{ and } 2/3) = 1/3$

$\Rightarrow x = x_1 + \Delta x u$ $y = y_1 + \Delta y u$

$\Rightarrow x = 3 + (3-3) \times 1/3, y = 7 + 1/3 \times 3$

$\Rightarrow x = 3, y = 8$

Sutherland Hodgeman Polygon Clipping



This is how we can create vertex list